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APPLICATION NO.	FILING DATE	FIRST NAMED INVENTOR	ATTORNEY DOCKET NO.	CONFIRMATION NO.
09/652,820	08/31/2000	John Oliensis	13725	4355

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EXAMINER

KIBLER, VIRGINIA M

ART UNIT	PAPER NUMBER
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2623

DATE MAILED: 05/20/2003

4

Please find below and/or attached an Office communication concerning this application or proceeding.

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Office Action Summary

Application No.

09/652,820

Applicant(s)

OLIENSIS, JOHN

Examiner

Virginia M Kibler

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-- The MAILING DATE of this communication appears on the cover sheet with the correspondence address --

Period for Reply

A SHORTENED STATUTORY PERIOD FOR REPLY IS SET TO EXPIRE 3 MONTH(S) FROM THE MAILING DATE OF THIS COMMUNICATION.

- Extensions of time may be available under the provisions of 37 CFR 1.136(a). In no event, however, may a reply be timely filed after SIX (6) MONTHS from the mailing date of this communication.
- If the period for reply specified above is less than thirty (30) days, a reply within the statutory minimum of thirty (30) days will be considered timely.
- If NO period for reply is specified above, the maximum statutory period will apply and will expire SIX (6) MONTHS from the mailing date of this communication.
- Failure to reply within the set or extended period for reply will, by statute, cause the application to become ABANDONED (35 U.S.C. § 133).
- Any reply received by the Office later than three months after the mailing date of this communication, even if timely filed, may reduce any earned patent term adjustment. See 37 CFR 1.704(b).

Status

- 1) ☐ Responsive to communication(s) filed on ____.
- 2a) ☐ This action is **FINAL**. 2b) ☒ This action is non-final.
- 3) ☐ Since this application is in condition for allowance except for formal matters, prosecution as to the merits is closed in accordance with the practice under *Ex parte Quayle*, 1935 C.D. 11, 453 O.G. 213.

Disposition of Claims

- 4) ☒ Claim(s) 1-13 is/are pending in the application.
- 4a) Of the above claim(s) ____ is/are withdrawn from consideration.
- 5) ☐ Claim(s) ____ is/are allowed.
- 6) ☒ Claim(s) 1-6 and 8 is/are rejected.
- 7) ☒ Claim(s) 5 and 7-13 is/are objected to.
- 8) ☐ Claim(s) ____ are subject to restriction and/or election requirement.

Application Papers

- 9) ☒ The specification is objected to by the Examiner.
- 10) ☒ The drawing(s) filed on 31 August 2000 is/are: a) ☒ accepted or b) ☐ objected to by the Examiner.
- Applicant may not request that any objection to the drawing(s) be held in abeyance. See 37 CFR 1.85(a).
- 11) ☐ The proposed drawing correction filed on ____ is: a) ☐ approved b) ☐ disapproved by the Examiner.
- If approved, corrected drawings are required in reply to this Office action.
- 12) ☐ The oath or declaration is objected to by the Examiner.

Priority under 35 U.S.C. §§ 119 and 120

- 13) ☐ Acknowledgment is made of a claim for foreign priority under 35 U.S.C. § 119(a)-(d) or (f).
- a) ☐ All b) ☐ Some * c) ☐ None of:
- ☐ Certified copies of the priority documents have been received.
 - ☐ Certified copies of the priority documents have been received in Application No. ____.
 - ☐ Copies of the certified copies of the priority documents have been received in this National Stage application from the International Bureau (PCT Rule 17.2(a)).
- * See the attached detailed Office action for a list of the certified copies not received.
- 14) ☐ Acknowledgment is made of a claim for domestic priority under 35 U.S.C. § 119(e) (to a provisional application).
- a) ☐ The translation of the foreign language provisional application has been received.
- 15) ☐ Acknowledgment is made of a claim for domestic priority under 35 U.S.C. §§ 120 and/or 121.

Attachment(s)

- | | |
|--|---|
| 1) <input checked="" type="checkbox"/> Notice of References Cited (PTO-892) | 4) <input type="checkbox"/> Interview Summary (PTO-413) Paper No(s). ____. |
| 2) <input type="checkbox"/> Notice of Draftsperson's Patent Drawing Review (PTO-948) | 5) <input type="checkbox"/> Notice of Informal Patent Application (PTO-152) |
| 3) <input checked="" type="checkbox"/> Information Disclosure Statement(s) (PTO-1449) Paper No(s) <u>4</u> . | 6) <input type="checkbox"/> Other: |

DETAILED ACTION

Specification

1. The abstract of the disclosure is objected to because of undue length and "The steps" should be changed to "the step" on line 14 and "afirst" should be changed to "a first" on line 24. Correction is required. See MPEP § 608.01(b).
2. The disclosure is objected to because of the following informalities: "09/653,023" should be inserted after "Serial No." on page 1, line 5; "9/1/00" should be inserted after "filed on" on page 1, line 7; "R_i" should be changed to "R" on page 8, line 14; and "(smoothed" should be changed to "(smoothed)" on page 9, line 3. The first paragraph on page 3 is almost identical to the preceding paragraph on page 2. It is suggested to delete the first para. on page 3.

Appropriate correction is required.

Double Patenting

3. The nonstatutory double patenting rejection is based on a judicially created doctrine grounded in public policy (a policy reflected in the statute) so as to prevent the unjustified or improper timewise extension of the "right to exclude" granted by a patent and to prevent possible harassment by multiple assignees. See *In re Goodman*, 11 F.3d 1046, 29 USPQ2d 2010 (Fed. Cir. 1993); *In re Longi*, 759 F.2d 887, 225 USPQ 645 (Fed. Cir. 1985); *In re Van Ornum*, 686 F.2d 937, 214 USPQ 761 (CCPA 1982); *In re Vogel*, 422 F.2d 438, 164 USPQ 619 (CCPA 1970); and, *In re Thorington*, 418 F.2d 528, 163 USPQ 644 (CCPA 1969).

A timely filed terminal disclaimer in compliance with 37 CFR 1.321(c) may be used to overcome an actual or provisional rejection based on a nonstatutory double patenting ground provided the conflicting application or patent is shown to be commonly owned with this application. See 37 CFR 1.130(b).

Effective January 1, 1994, a registered attorney or agent of record may sign a terminal disclaimer. A terminal disclaimer signed by the assignee must fully comply with 37 CFR 3.73(b).

4. Claim 1 is provisionally rejected under the judicially created doctrine of obviousness-type double patenting as being unpatentable over claim 1 of copending Application No. 09/653,023 in view of Aguiar et al. (*Factorization as a Rank 1 Problem*) and in further view of Irani (*Multi-Frame Optical Flow Estimation Using Subspace Constraints*).

Regarding claim 1 of the instant application, claim 1 of 09/653,023 covers equivalent subject matter except for the limitations regarding rank-1 factorization and dividing the successive images into smoothing windows. Using rank-1 factorization rather than rank-3 factor matrices is known in the art as evidenced by Aguiar et al. (Abstract, lines 1-12). Therefore, it would have been obvious to one of ordinary skill in the art at the time of the invention to have modified the rank-3 factor matrices of claim 1 of 09/653,023 in view of Aguiar et al. in order to allow the use of fast algorithms (Abstract, lines 11-13). Dividing the images into smoothing windows is also known in the art as evidenced by Irani (Sect. 3.2, Para. 1). Therefore, it would have been obvious to one of ordinary skill in the art at the time of the invention to have modified claim 1 of 09/653,023 in view of Irani to include dividing into smoothing windows in order to simplify computations (Sect. 3.2, Para. 2).

This is a provisional obviousness-type double patenting rejection.

Claim Objections

5. Claim 5 is objected to because of the following informalities: “}” should be added before “where” on page 18, line 21 and “matrix with” should be changed to “matrix” on page 19, line 9. Appropriate correction is required.

6. Claim 8 is objected to because of the following informalities: “cameras optical” should be changed to “camera’s optical” on page 21, line 2. Appropriate correction is required

Claim Rejections - 35 USC § 103

7. The following is a quotation of 35 U.S.C. 103(a) which forms the basis for all obviousness rejections set forth in this Office action:

(a) A patent may not be obtained though the invention is not identically disclosed or described as set forth in section 102 of this title, if the differences between the subject matter sought to be patented and the prior art are such that the subject matter as a whole would have been obvious at the time the invention was made to a person having ordinary skill in the art to which said subject matter pertains. Patentability shall not be negated by the manner in which the invention was made.

8. Claims 1-6 and 8 are rejected under 35 U.S.C. 103(a) as being unpatentable over Oliensis et al. (*Structure from Motion using Points, Lines, and Intensities*) in view of Aguiar et al. (*Factorization as a Rank 1 Problem*).

Regarding claim 1, Oliensis et al. (“Oliensis”) discloses a method for recovering 3D scene structure and camera motion from image data obtained from a multi-image sequence (Sect.1, para. 1). Oliensis discloses determining image data shifts for each successive image with respect to the reference image, the shifts being derived from the camera translation and/or rotation from the reference perspective to the successive different perspectives (Sect. 3.1). Oliensis further discloses constructing a shift data matrix that incorporates the image data shifts for each image and calculating a factorization of the shift data matrix using SVD corresponding to the 3D structure and size of the camera motion (Sect. 1, para. 7), recovering the direction of camera motion from the first vector corresponding to the 3D structure by solving a linear equation and recovering the 3D structure by solving a linear equation using the recovered camera motion (Sect. 3.5). Oliensis discloses that it is known to divide the successive images into

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smoothing windows (Sect. 3.6, para. 5). Therefore, it would have been obvious to one of ordinary skill in the art at the time of the invention to applied to smoothing windows to the successive images in order to apply the smoothing constraint. Oliensis does not recognize calculating a rank-1 factorization from the shift data matrix. However, Aguiar et al. ("Aguiar") teaches that it is known to use rank-1 factorization rather than rank-3 (Abstract, lines 1-12). Therefore, it would have been obvious to one of ordinary skill in the art at the time of the invention to have modified the rank-3 disclosed by Oliensis to use rank-1 factorization, as taught by Aguiar, in order to allow the use of fast algorithms (Abstract, lines 11-13).

Regarding claim 2, Oliensis discloses computing a first projection matrix (Sect. 3.3, para. 7), recovering camera rotation vectors from the shift data matrix and the first projection matrix (Sect. 3.5). Oliensis further discloses computing a second projection matrix (Sect. 3.3, para. 7) and recovering the direction of camera translation using the shift data matrix, the reference image, the second projection matrix and the recovered camera rotation vectors (Sect. 3.5).

Regarding claim 3, Oliensis discloses recovering the 3D structure from the shift data matrix, the reference image, the recovered camera rotation vectors, and the recovered direction of translation vectors (Sect. 3.5).

Regarding claim 4, Oliensis discloses recovering the rotations of the camera between each successive image and warping all images in the sequence toward the reference image while neglecting the translations (Sect. 3.1, para. 2).

Regarding claim 5, Oliensis discloses computing H and D_{CH} or " Δ_{CH} " (Sect. 3.5. para. 4) where H is a $(N_P - 3) \times N_P$ matrix defined so that HH^T is the identity matrix and H annihilates the three vectors ψ_x, ψ_y, ψ_z (Sect. 3.5, para. 1) where the three vectors are computed from the

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reference image as recited on page 18, line 21 of Claim 5 (Sect. 3.4, bottom of page 601) where

$r^{(1)}(x,y)$, $r^{(2)}(x,y)$, and $r^{(3)}(x,y)$ are defined as recited on page 19, line 1 of Claim 5 (Sect. 3.2).

Oliensis discloses Δ as a shift data matrix that gives the difference in intensities between each successive image and the reference image (Sect. 1, para. 7) and is a $(N_1 - 1) \times N_p$ matrix with

entires ΔI_n^i (Sect. 3.5) where ΔI_n^i is the change in (smoothed) intensity with respect to the

reference image and with respect to the reference image and with no smoothing $\Delta I_n^i = I_n^i - I_n^0$

(Sect. 3.4, Para. 2) where N_1 is the number of images (Sect. 2, para. 2), N_p is the number of

pixels and where I^i denotes the i -th image with $i=0,1,\dots,N_1 - 1$ (Sect. 2, para. 5) where $I_n^i = I^i(p_n)$

denotes the image intensity at the n -th pixel position in I^i where I^0 is the reference image where x

and y are the image coordinates of the pixel position and $p=(x,y)$ (Sect. 2, para. 5) and where Δ_{CH}

$= C^{-1/2} \Delta H^T$ where C is a constant matrix (Sect. 3.5) and where the notation $\{V\}$ used to denote a

vector with elements given by V^a (Sect. 2, para. 6).

Regarding claim 6, Aguiar discloses computing a rank-1 factorization $\Delta_{CH} = M^{(1)} S^{(1)T}$ where $M^{(1)}$ and $S^{(1)T}$ are vectors corresponding to motion and structure (Sect. 3, page 180).

Regarding claim 8, Oliensis discloses setting Z_n^{-1} as constant within each window, where Z is the depth from the camera to a 3D scene along the camera's optical axis (Sect. 3.6, para. 5) and listing each of the pixels so that those in the k -th smoothing window have sequential indices (Sect. 2, para. 5).

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Allowable Subject Matter

9. Claims 7 and 9-13 are objected to as being dependent upon a rejected base claim, but would be allowable if rewritten in independent form including all of the limitations of the base claim and any intervening claims.

Conclusion

10. The prior art made of record and not relied upon is considered pertinent to applicant's disclosure.

Wang et al., "A SVD Decomposition of Essential Matrix with Eight Solutions for the Relative Positions of Two Perspective Cameras"

Diamantaras et al., "Camera Motion Parameter Recovery Under Perspective Projection"
and

Kung et al., "An SVD Approach to Multi-Camera-Multi-Target 3D Motion-Shape Analysis."

Contact Information

11. Any inquiry concerning this communication or earlier communications from the examiner should be directed to Virginia M Kibler whose telephone number is (703) 306-4072. The examiner can normally be reached on Mon. - Thurs. 8:00 - 5:30 and every other Friday.


If attempts to reach the examiner by telephone are unsuccessful, the examiner's supervisor, Amelia Au can be reached on (703) 308-6604. The fax phone numbers for the

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organization where this application or proceeding is assigned are (703) 872-9314 for regular communications and (703) 872-9314 for After Final communications.

Any inquiry of a general nature or relating to the status of this application or proceeding should be directed to the receptionist whose telephone number is (703) 306-0377.

VK
May 16, 2003


AMELIA M. AU
SUPERVISORY PATENT EXAMINER
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